

# dynamics of logistic networks



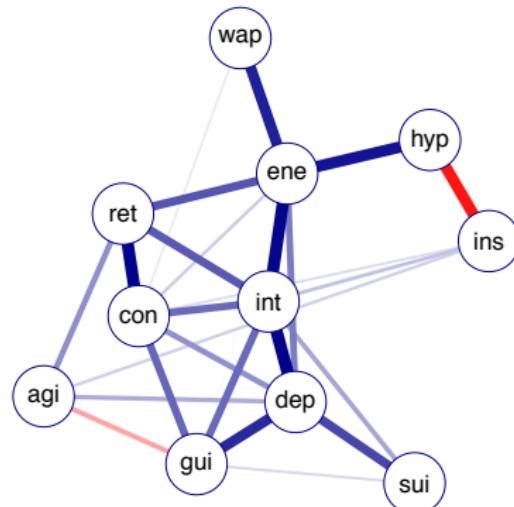
$p_\Phi$

Lourens Waldorp

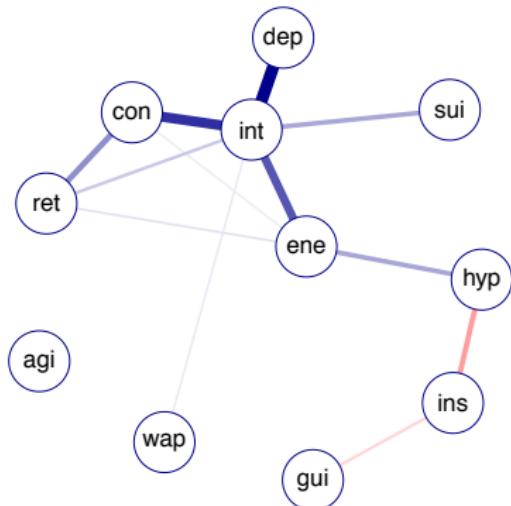
University of Amsterdam

$p(\text{active}|\text{MB}) = 0.15$

# pathologies and network structure



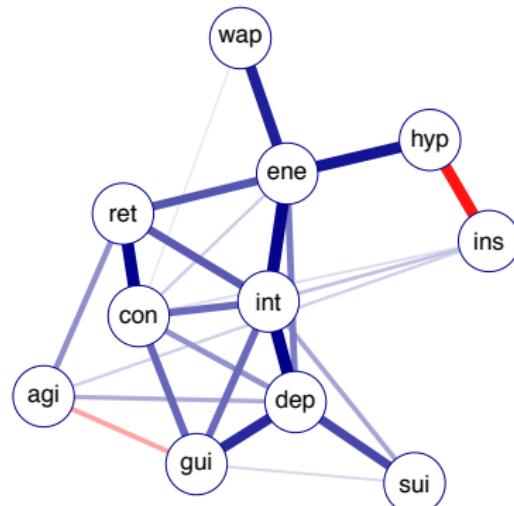
persisters



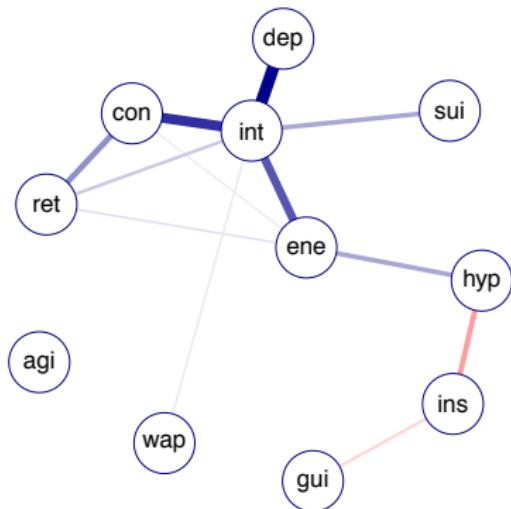
remitters

- stronger and more connectivity in persisters

# pathologies and network structure



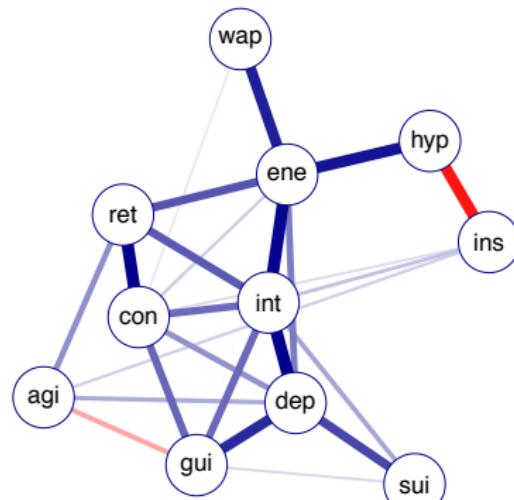
persisters



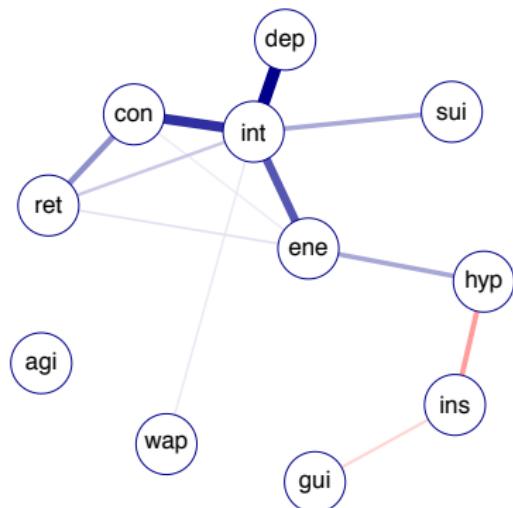
remitters

- stronger and more connectivity in persisters
- what does the network structure say about (long term) behaviour?

# pathologies and network structure



persisters



remitters

- stronger and more connectivity in persisters
- what does the network structure say about (long term) behaviour?
- what are the dynamics of a particular network structure?

# cellular automaton



- each node is on or off (0/1 networks)
- at time  $t = 0$  two neighbours are active

# cellular automaton



- each node is on or off (0/1 networks)
- at time  $t = 0$  two neighbours are active
- local rule: then at  $t = 1$  middle node is active

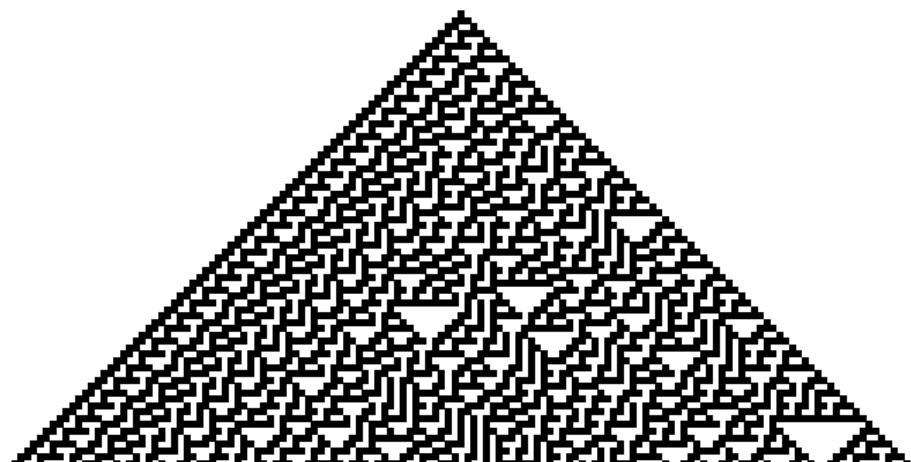
# cellular automaton



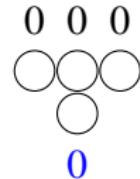
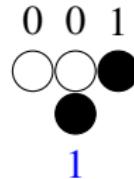
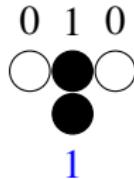
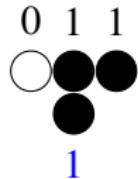
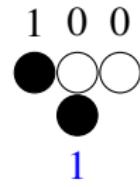
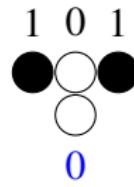
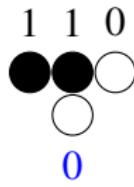
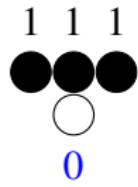
- each node is on or off (0/1 networks)
- at time  $t = 0$  two neighbours are active
- local rule: then at  $t = 1$  middle node is active
- or, at time  $t = 1$  the middle is inactive

# elementary (Wolfram) automaton

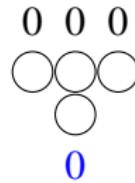
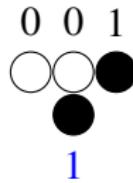
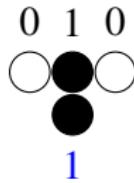
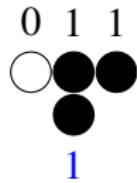
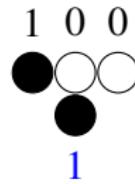
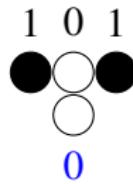
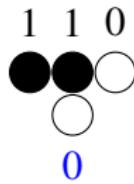
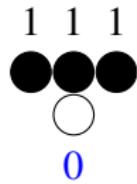
**Rule 30**  
**( $k = 2$ ,  $r = 1$ , 70 steps)**



# cellular automaton rule 30

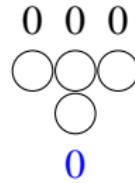
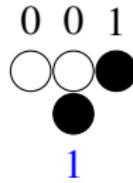
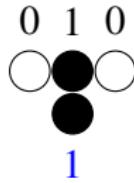
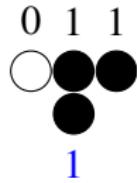
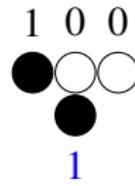
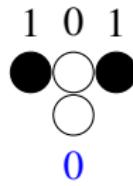
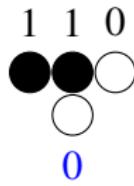
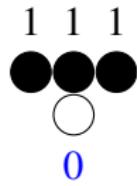


# cellular automaton rule 30



$$0 \cdot 2^7 + 0 \cdot 2^6 + 0 \cdot 2^5 + 1 \cdot 2^4 + 1 \cdot 2^3 + 1 \cdot 2^2 + 1 \cdot 2^1 + 0 \cdot 2^0$$

# cellular automaton rule 30



$$0 \cdot 2^7 + 0 \cdot 2^6 + 0 \cdot 2^5 + 1 \cdot 2^4 + 1 \cdot 2^3 + 1 \cdot 2^2 + 1 \cdot 2^1 + 0 \cdot 2^0$$

(base 2) 00011110 = (base 10) 30

# cellular automaton

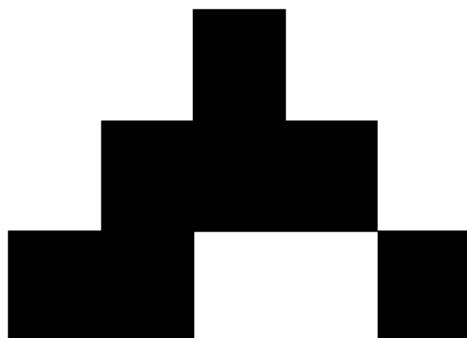
**Rule 30**  
 $(k = 2, r = 1, 1 \text{ steps})$



- neighbours 'infect' you
- local rule: a pattern of neighbours are infected, you will be infected; otherwise, not infected

# cellular automaton

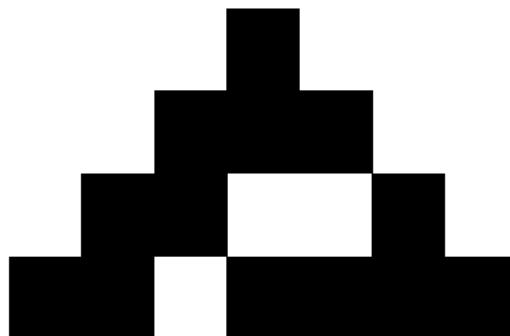
Rule 30  
( $k = 2, r = 1, 2$  steps)



- neighbours 'infect' you
- local rule: a pattern of neighbours are infected, you will be infected; otherwise, not infected

# cellular automaton

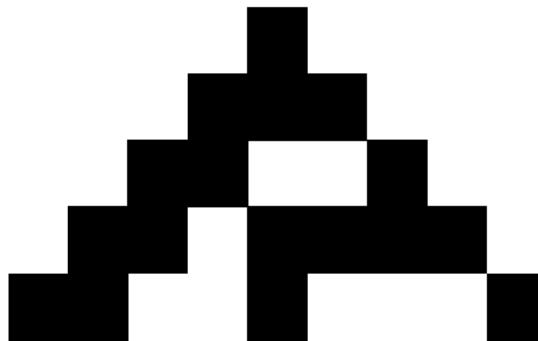
Rule 30  
( $k = 2, r = 1, 3$  steps)



- neighbours 'infect' you
- local rule: a pattern of neighbours are infected, you will be infected; otherwise, not infected

# cellular automaton

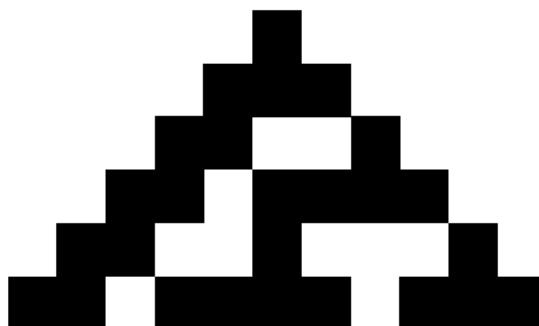
Rule 30  
( $k = 2, r = 1, 4$  steps)



- neighbours 'infect' you
- local rule: a pattern of neighbours are infected, you will be infected; otherwise, not infected

# cellular automaton

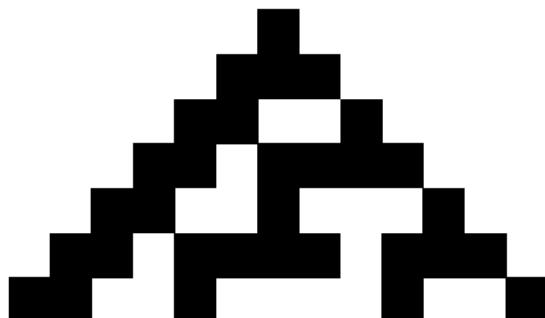
Rule 30  
( $k = 2$ ,  $r = 1$ , 5 steps)



- neighbours 'infect' you
- local rule: a pattern of neighbours are infected, you will be infected; otherwise, not infected

# cellular automaton

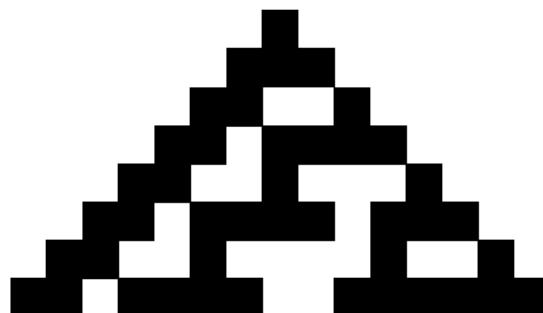
Rule 30  
( $k = 2, r = 1, 6$  steps)



- neighbours 'infect' you
- local rule: a pattern of neighbours are infected, you will be infected; otherwise, not infected

# cellular automaton

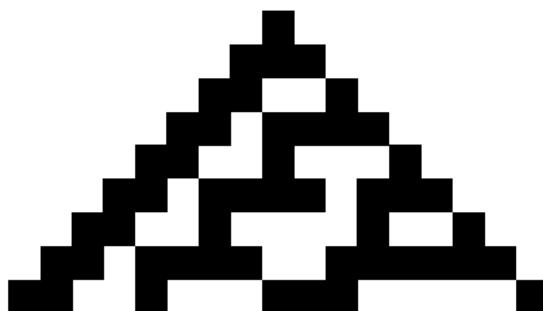
Rule 30  
( $k = 2$ ,  $r = 1$ , 7 steps)



- neighbours 'infect' you
- local rule: a pattern of neighbours are infected, you will be infected; otherwise, not infected

# cellular automaton

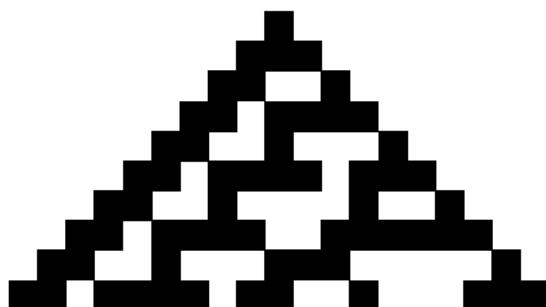
Rule 30  
( $k = 2, r = 1, 8$  steps)



- neighbours 'infect' you
- local rule: a pattern of neighbours are infected, you will be infected; otherwise, not infected

# cellular automaton

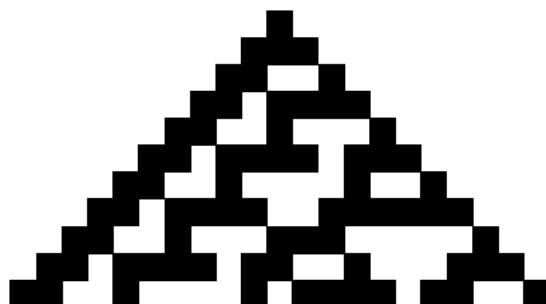
Rule 30  
( $k = 2, r = 1, 9$  steps)



- neighbours 'infect' you
- local rule: a pattern of neighbours are infected, you will be infected; otherwise, not infected

# cellular automaton

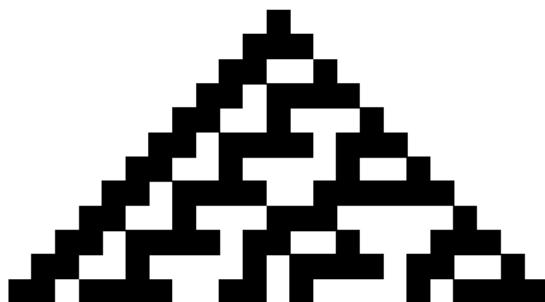
Rule 30  
( $k = 2, r = 1, 10$  steps)



- neighbours 'infect' you
- local rule: a pattern of neighbours are infected, you will be infected; otherwise, not infected

# cellular automaton

Rule 30  
( $k = 2$ ,  $r = 1$ , 11 steps)



- neighbours 'infect' you
- local rule: a pattern of neighbours are infected, you will be infected; otherwise, not infected

# cellular automaton

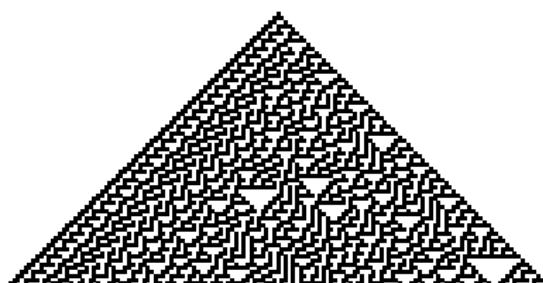
Rule 30  
( $k = 2$ ,  $r = 1$ , 12 steps)



- neighbours 'infect' you
- local rule: a pattern of neighbours are infected, you will be infected; otherwise, not infected

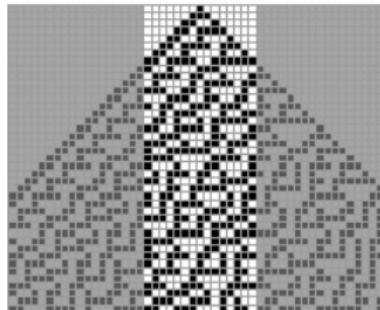
# cellular automaton

Rule 30  
( $k = 2$ ,  $r = 1$ , 70 steps)

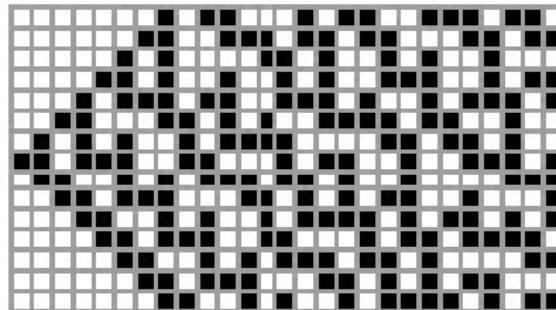


- neighbours 'infect' you
- local rule: a pattern of neighbours are infected, you will be infected; otherwise, not infected

# cellular automaton music



slice of rule 30

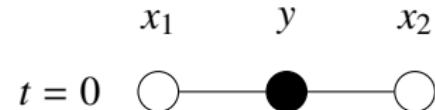


slice sideways

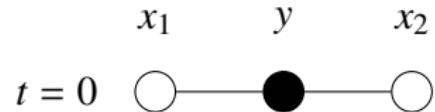
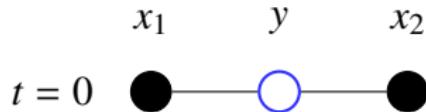


music scale applied to rule 30

# cellular automaton

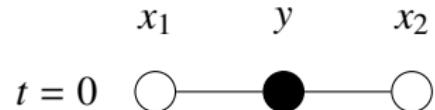


# cellular automaton



$$\mathbb{P}(y = 1 \mid x) = \frac{\exp(\beta_0 + \beta_1 x_1 + \beta_2 x_2)}{1 + \exp(\beta_0 + \beta_1 x_1 + \beta_2 x_2)}$$

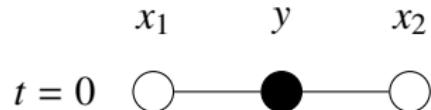
## cellular automaton



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log-odds :  $\frac{\mathbb{P}(y = 1 \mid x)}{\mathbb{P}(y = 0 \mid x)} = \beta_0 + \beta_1 x_1 + \beta_2 x_2$

## cellular automaton



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log-odds :  $\frac{\mathbb{P}(y = 1 \mid x)}{\mathbb{P}(y = 0 \mid x)} = \beta_0 + \beta_1 x_1 + \beta_2 x_2$

This is the Ising model (conditional version).

## cellular automaton

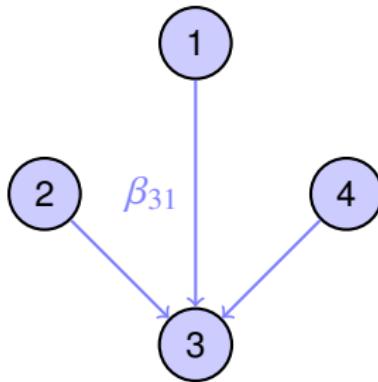
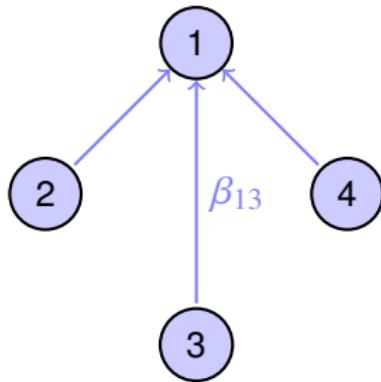


log-likelihood

$$\begin{aligned}\ell(\theta) &= \frac{1}{n} \sum_{i=1}^n \log \mathbb{P}(y_i = 1 | x_i) \\ &= \frac{1}{n} \sum_{i=1}^n y_i \mu(x_i) - (1 + \exp(\mu(x_i)))\end{aligned}$$

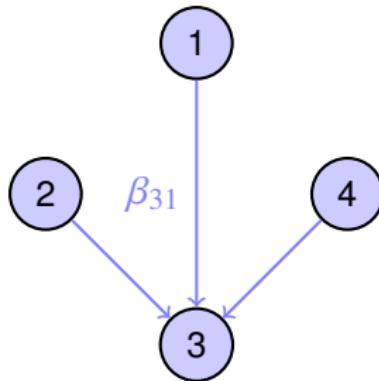
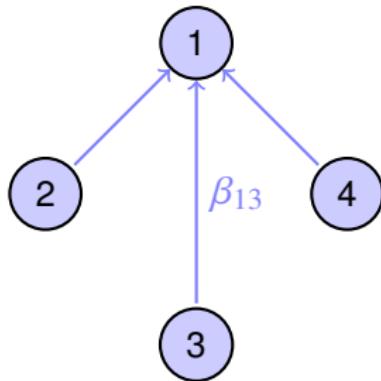
and  $\mu(x_i) = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2}$  and  $\theta = (\beta_0, \beta_1, \beta_2)$

## nodewise regression



combine neighborhoods

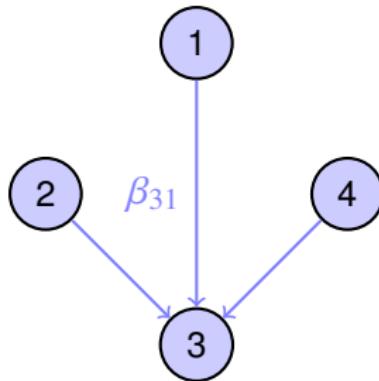
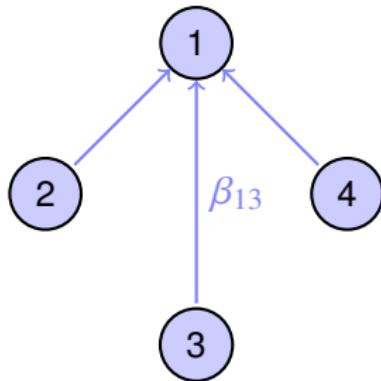
## nodewise regression



combine neighborhoods

- and node  $X_3$  is in  $\text{ne}(1)$  if  $\beta_{13} \neq 0$  and  $\beta_{31} \neq 0$

# nodewise regression



combine neighborhoods

- and node  $X_3$  is in  $\text{ne}(1)$  if  $\beta_{13} \neq 0$  and  $\beta_{31} \neq 0$
- or node  $X_3$  is in  $\text{ne}(1)$  if  $\beta_{13} \neq 0$  or  $\beta_{31} \neq 0$

## solution when $p > n$

penalized likelihood

$$\ell(\theta) = \frac{1}{n} \sum_{i=1}^n \log \mathbb{P}(y_i = 1 | x_i) + \lambda \psi(\beta)$$

model fit    penalty

# solution when $p > n$

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model fit                                      penalty

## types of penalization

### ridge

---

$\psi$	$\sum_{i=1}^n \beta_i^2$
bias	all $\beta_i$
treats $\beta$ s	unequally

---

# solution when $p > n$

## penalized likelihood

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model fit                                    penalty

## types of penalization

	ridge	lasso
$\psi$	$\sum_{i=1} \beta_i^2$	$\sum_{i=1}  \beta_i $
bias	all $\beta_i$	small $\beta_i$
treats $\beta$ s	unequally	equally

# solution when $p > n$

## penalized likelihood

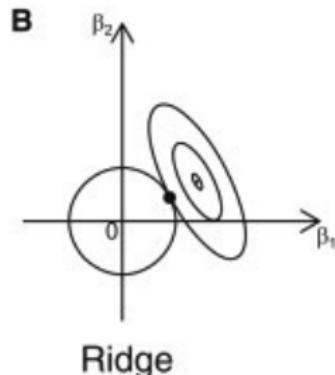
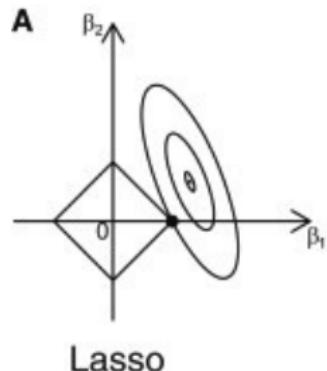
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model fit   penalty

## types of penalization

	ridge	lasso	$\ell_0$
$\psi$	$\sum_{i=1} \beta_i^2$	$\sum_{i=1}  \beta_i $	$p$
bias	all $\beta_i$	small $\beta_i$	all $\beta_i$
treats $\beta$ s	unequally	equally	equally

## solution when $p > n$



## types of penalization

	ridge	lasso	$\ell_0$
$\psi$	$\sum_{i=1} \beta_i^2$	$\sum_{i=1}  \beta_i $	$p$
bias	all $\beta_i$	small $\beta_i$	all $\beta_i$
treats $\beta$ s	unequally	equally	equally

## dependent measures of effect

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correct rejections/true edges (true positive rate)

$$\text{recall} := \frac{|\hat{E} \cap E_0|}{|E_0|}$$

# dependent measures of effect

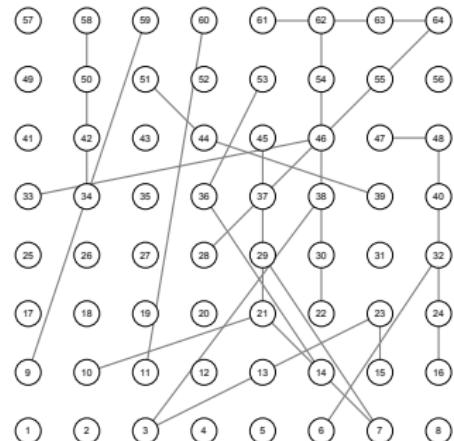
correct rejections/true edges (true positive rate)

$$\text{recall} := \frac{|\hat{E} \cap E_0|}{|E_0|}$$

correct rejections/rejections (positive predictive value)

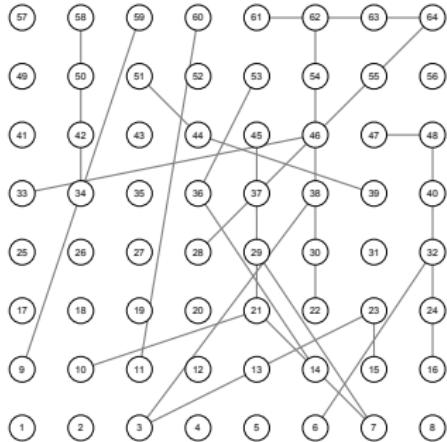
$$\text{precision} := \frac{|\hat{E} \cap E_0|}{|\hat{E}|}$$

# ER graph

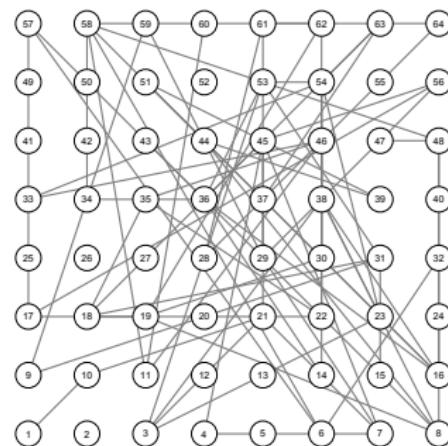


true graph

# ER graph

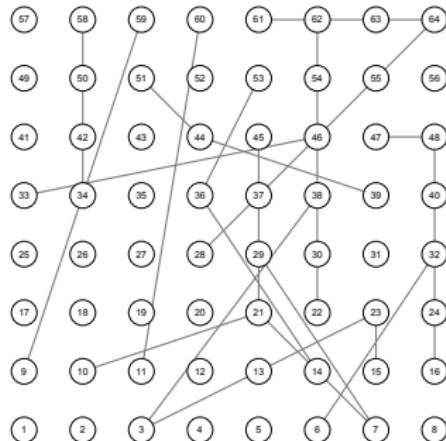


true graph

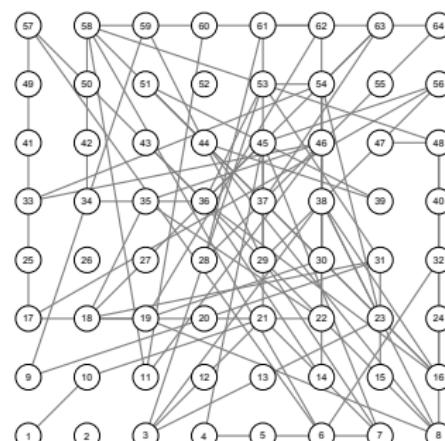


MB lasso

# ER graph



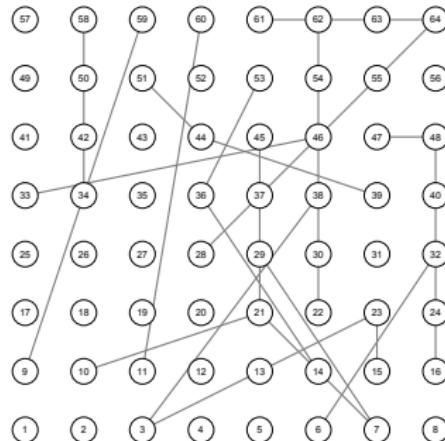
true graph



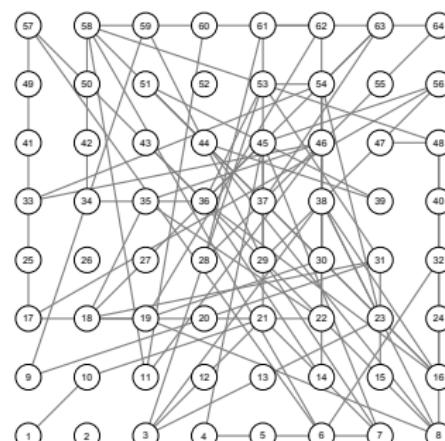
MB lasso

precision	recall	rejection rate	density
0.26	0.98	0.077	0.010

# ER graph



true graph

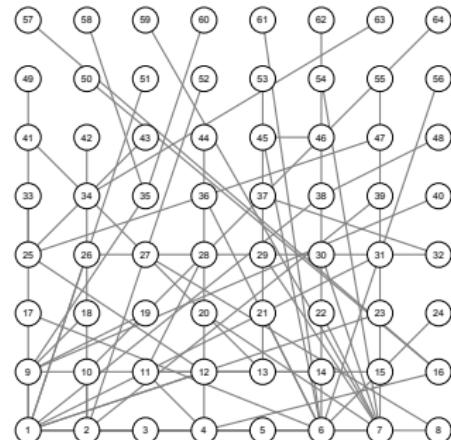


MB lasso

precision	recall	rejection rate		density
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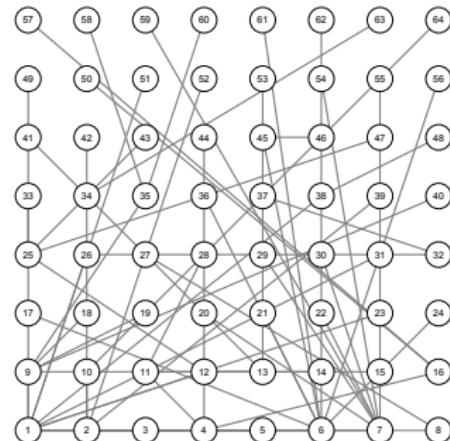
- often with lasso  $S_0 \subseteq S(\hat{\beta}_L)$  when penalty is 'small'  
[see Bühlmann & van de Geer, 2011]

# BA graph

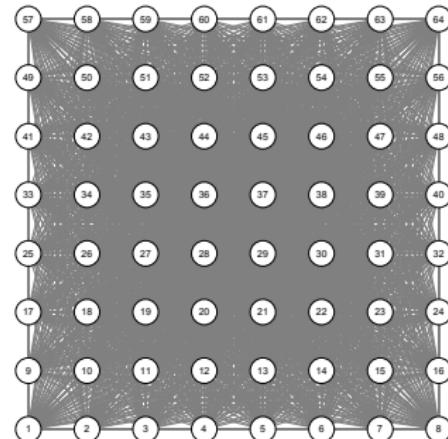


true graph

# BA graph

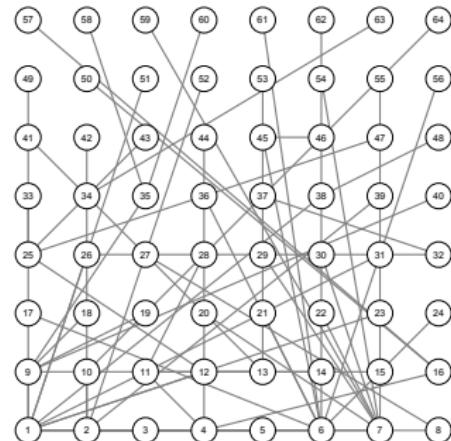


true graph

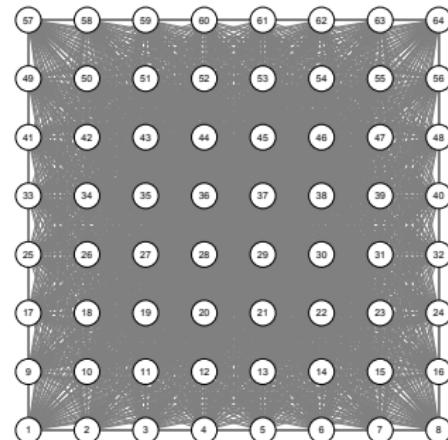


MB lasso

# BA graph



true graph



MB lasso

precision	recall	rejection rate	density
0.032	1.00	0.99	0.0625

# assumptions lasso

# assumptions lasso

## assumptions

(a) **sparsity** number  $s_0 = |\{j : \beta_{0j} \neq 0\}|$  cannot be large

$$|\{j : \beta_{0j} \neq 0\}| \leq \sqrt{\frac{n}{\log(p)}}$$

# assumptions lasso

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(b) **consistency** ( $\hat{\beta} \rightarrow \beta_0$ )

$$\lambda \geq \sqrt{\frac{\log(p)}{n}} \quad (\text{tuning})$$

# assumptions lasso

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$$\|\beta_{S_0}\|_1^2 \leq \frac{s_0}{\phi_0^2} \beta' X' X \beta \quad (\text{compatibility})$$

# classification and loss

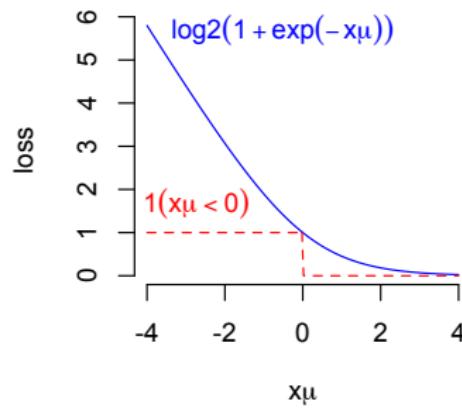
## classification

If  $\mathbb{P}(y = 1 | x) > 1/2$  then  $\mu = \beta_0 + \beta_1 x_1 + \beta_2 x_2 > 0$ . Hence

$$C(y) = 1\{\mu > 0\} \quad (1)$$

replaced by (using  $x \in \{-1, 1\}$  instead of  $x \in \{0, 1\}$ )

$$\psi(x, \mu) = \log(1 + \exp(-x\mu))$$



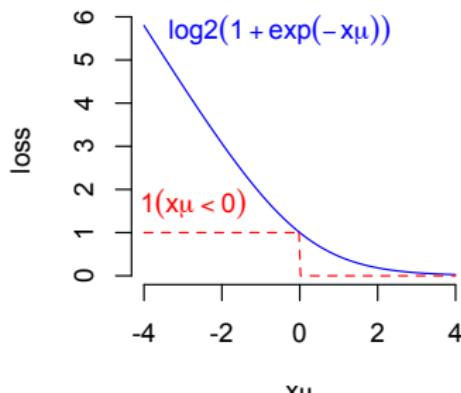
## classification and loss

## **prediction loss**

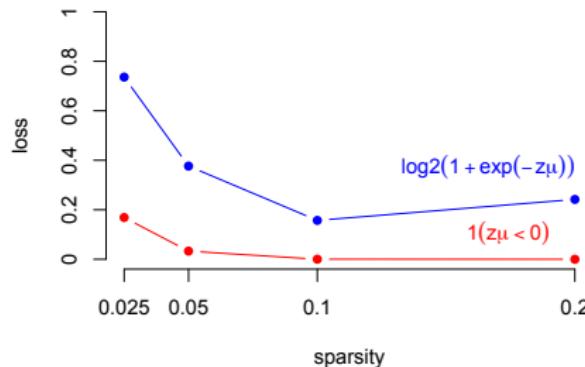
$$\mathcal{L}_\psi(\mu) = \frac{1}{n} \sum_{i=1}^n \mathbb{E}(\text{random part} - \text{optimal } \mu^* \text{ fixed})$$

where

$$\psi(x, \mu) = \log(1 + \exp(-x\mu))$$

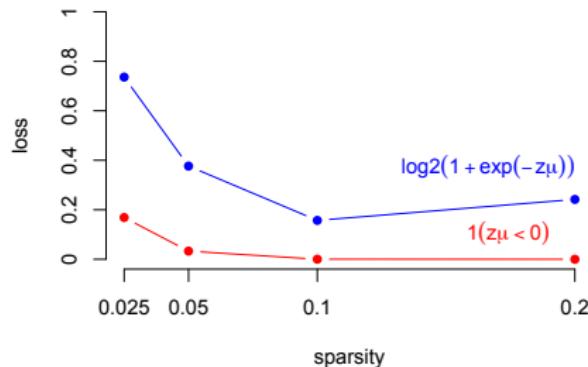


# ER graph

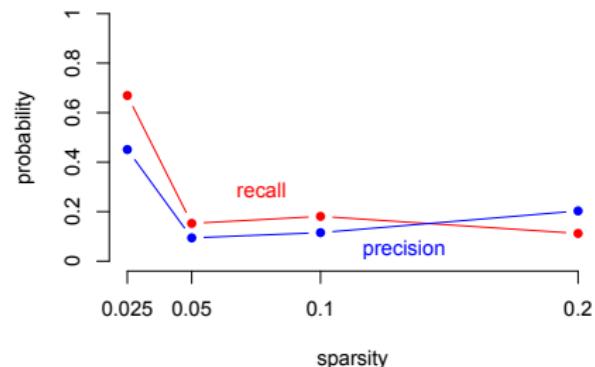


prediction loss

# ER graph

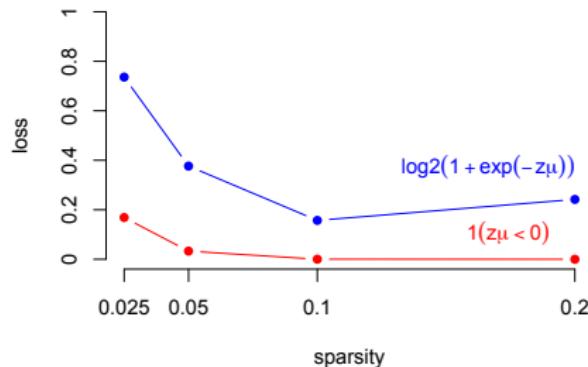


prediction loss

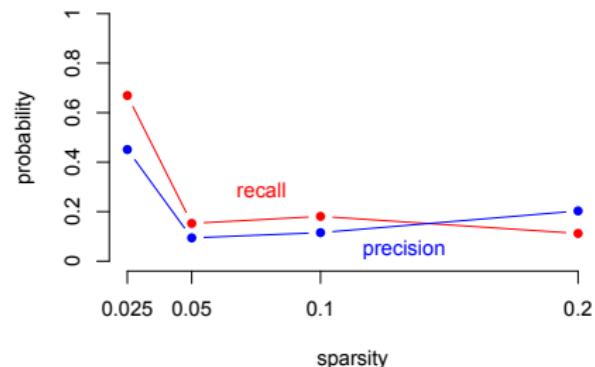


precision/recall

# ER graph



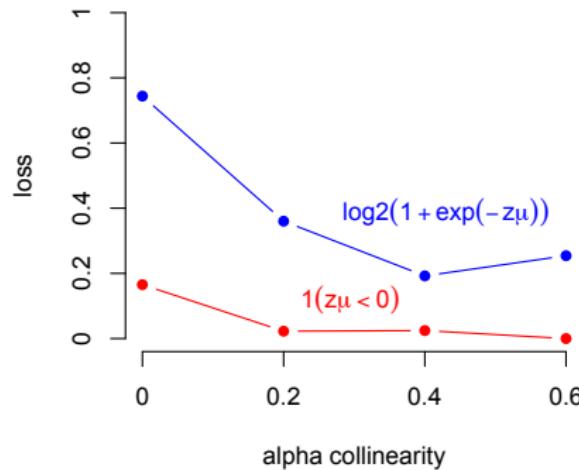
prediction loss



precision/recall

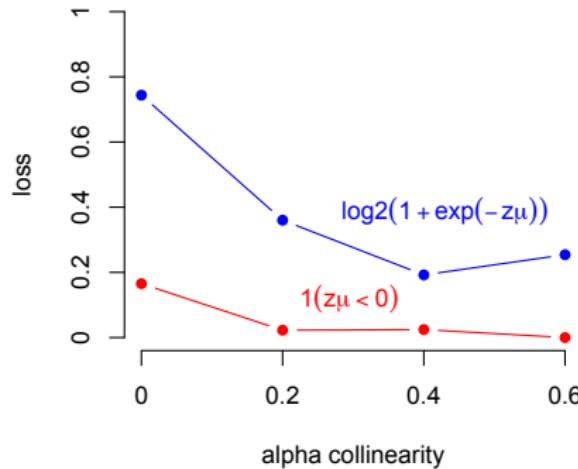
loss	recall	precision	density
0.21	0.19	0.15	0.10

# ER graph

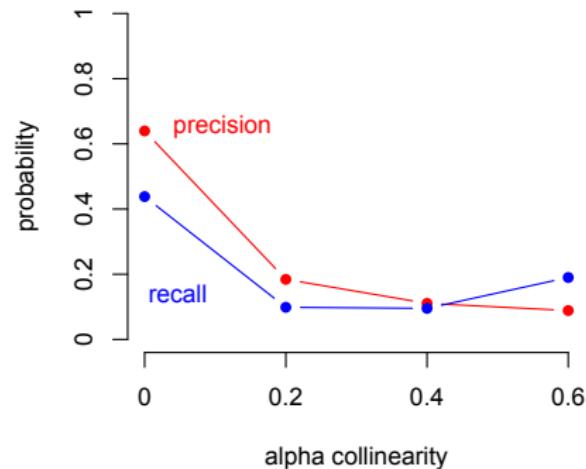


prediction loss

# ER graph

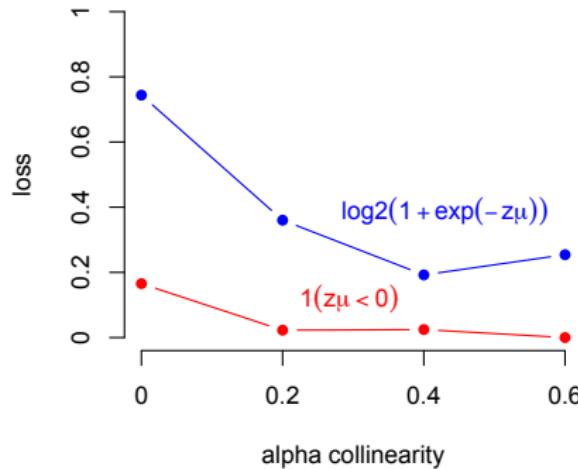


prediction loss

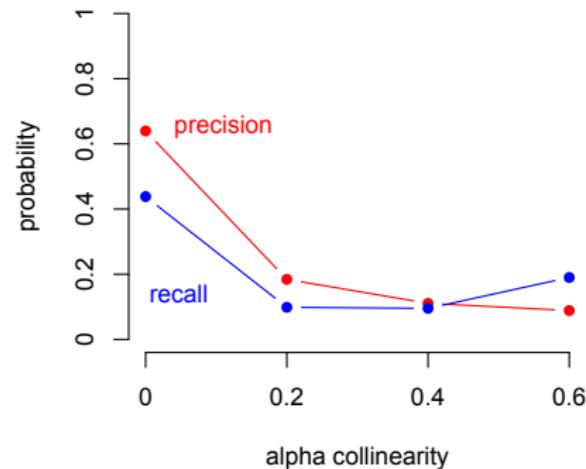


precision/recall

# ER graph



prediction loss



precision/recall

loss	recall	precision	% collinear
0.21	0.18	0.18	0.40

## Theorem (Waldorp, Marsman, Maris)

Let  $\mathcal{L}_\psi$  be the prediction error (loss). Let  $\theta \mapsto \mu_\theta(x)$  be the linear function in the Ising model and  $\hat{\theta}$  is the lasso estimate obtained with  $\lambda \geq 2\lambda_0$ . Given the same assumptions as in Lemma 1, we obtain

$$\mathcal{L}_\psi(\hat{\mu}) \leq 2\lambda M \|\hat{\theta} - \theta\|_1$$

- prediction error is smaller than estimation error
- prediction error requires fewer assumptions than estimation error
- prediction error is easier than estimation error
- prediction teaches you nothing about the system under investigation