



Recap: Supervised learning

Statistical learning reading group

Alexander Ly



Psychological Methods
University of Amsterdam

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Overview

- 1 Last year: Supervised learning
- 2 This year: More topics and applications
- 3 Organisation
- 4 Next meeting



Problem statement: Supervised learning

Based on n pairs of data $(x_1, y_1), \dots, (x_n, y_n)$, where x_i are features (input) and y_i are outcomes (output), predict future outcomes y_{new} given x_{new} .

Assumptions of mean regression

- There exists a true function f^* such that

$$y = f^*(x) + \epsilon \quad (1)$$

where ϵ is an error and $E(\epsilon) = 0$.

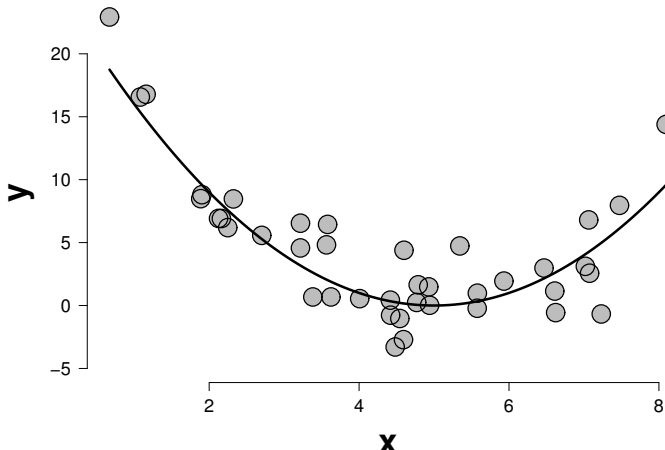
- Goal 1: Give a “best guess” $\hat{f}(x)$ of the unknown true f^* .
- Goal 2: Based on the best guess $\hat{f}(x)$, estimate a prediction error.



Goal of supervised learning

Example: Data generated from $f^*(x) = (x - 5)^2 + \epsilon$

True data generating $f^*(x) = (x - 5)^2 + \epsilon$, where $\epsilon \sim \mathcal{N}(0, 2^2)$



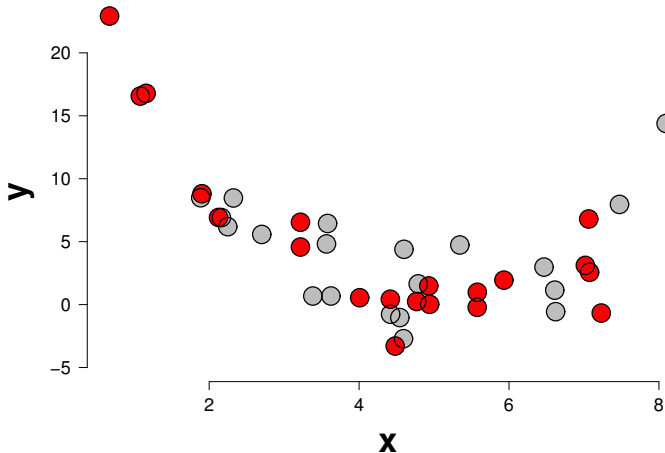
Underfitting

In this case, we know

- True $f^*(x) = (x - 5)^2 + \epsilon$
- Thus, misspecification
 $f^* \notin \mathcal{F}_2 := \left\{ f(x) = \theta_0 + \theta_1 x \mid \theta \in \mathbb{R}^2 \right\}$.
- In fact, underfitting
- Why not take a bigger set candidate collection \mathcal{F} ?
- Try $\mathcal{F}_3 := \left\{ f(x) = \theta_0 + \theta_1 x + \theta_2 x^2 \mid \theta \in \mathbb{R}^3 \right\}$

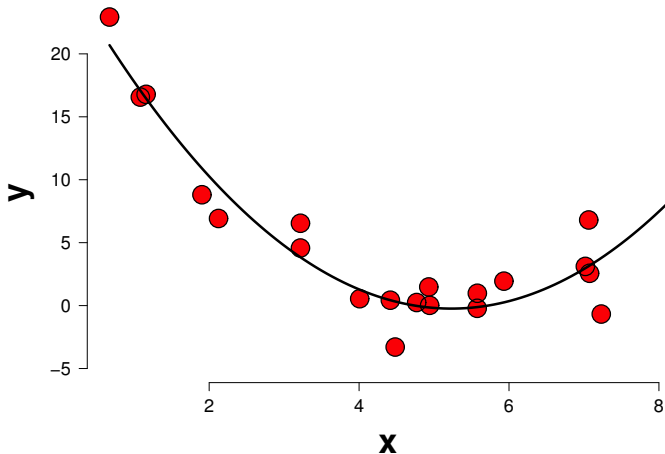
Goal of supervised learning

Sample splitting: Training set vs test set



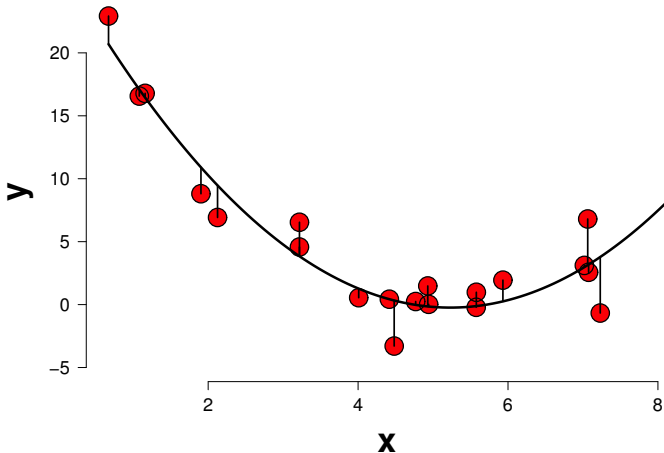
Goal of supervised learning

Learning on training set: Estimate the best fit



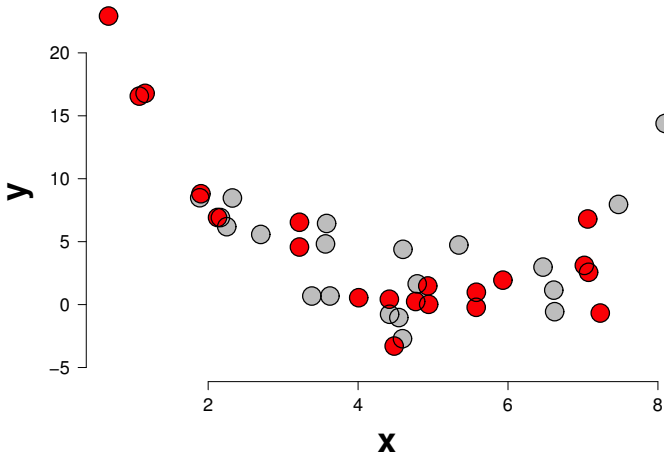
Goal of supervised learning

Learning on training set: In-sample error: 1.98



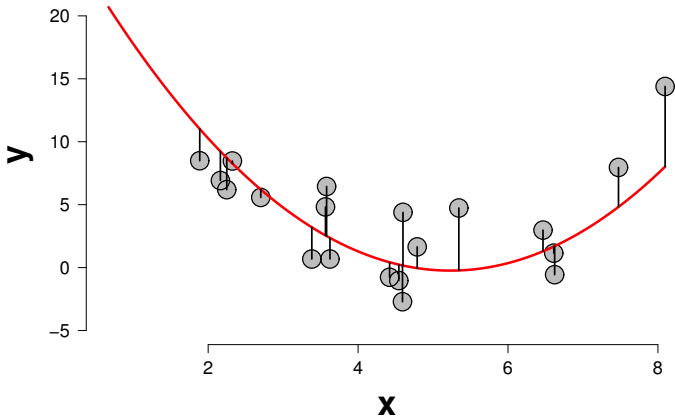
Goal of supervised learning

Prediction based on test set



Goal of supervised learning

Generalisation: Out-of-sample error: 2.86



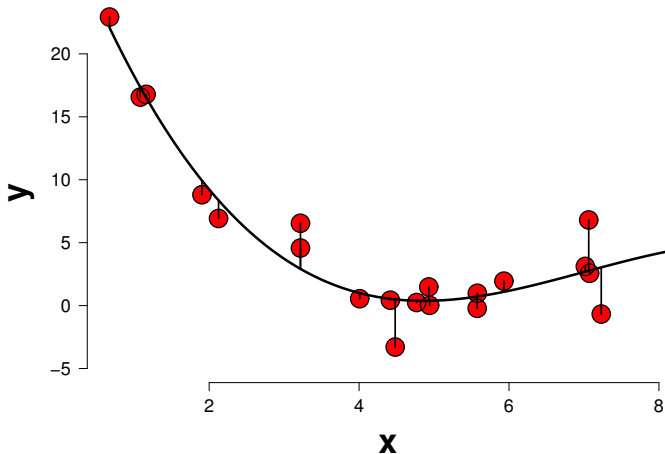
Reality

- We do not know the true f^*
- Why not try to use

$$\mathcal{F}_p := \left\{ \theta_0 + \theta_1 x^1 + \dots + \theta_{p-1} x^{p-1} \mid \theta \in \mathbb{R}^p \right\}$$

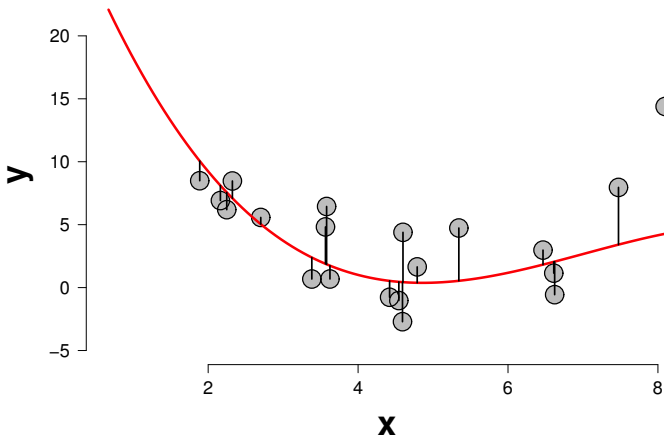
- Overfitting :(

Goal of supervised learning

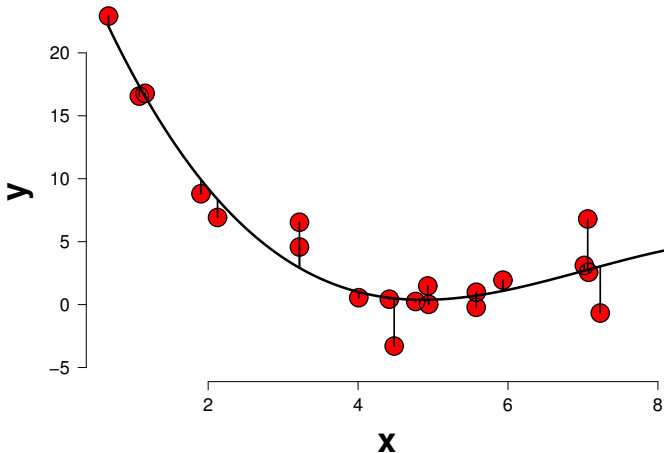
Learning on training set $p = 4$: In-sample error: 1.85

Goal of supervised learning

Generalisation: Out-of-sample error $p = 4$: 3.33

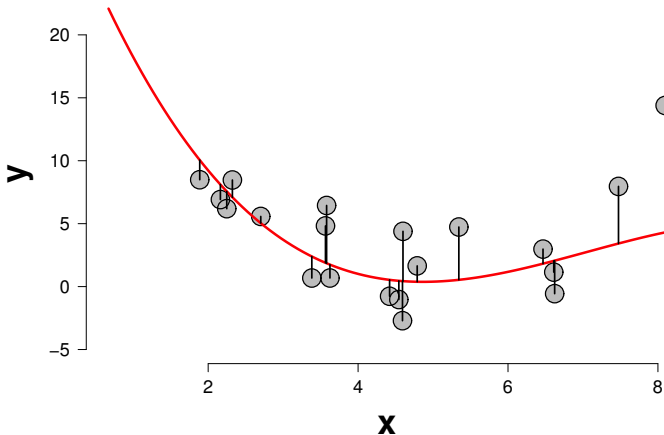


Goal of supervised learning

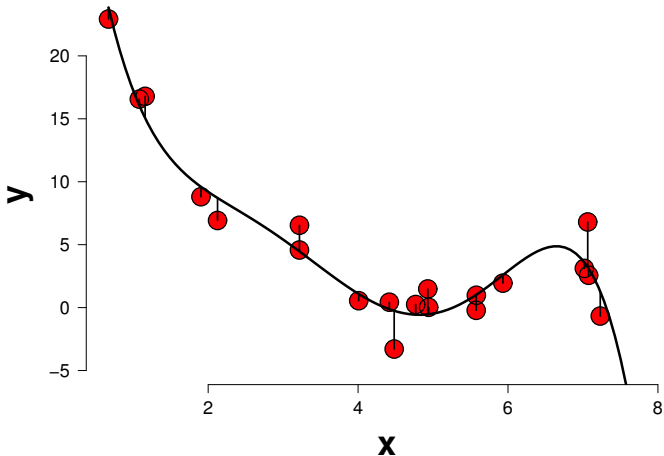
Learning on training set $p = 5$: In-sample error: 1.85

Goal of supervised learning

Generalisation: Out-of-sample error $p = 5$: 3.29

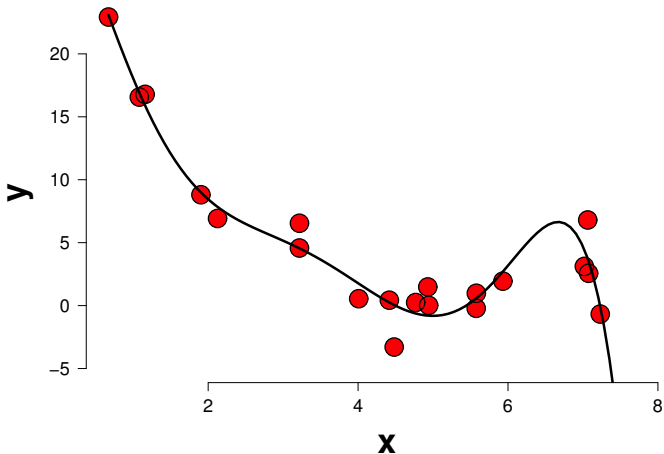


Goal of supervised learning

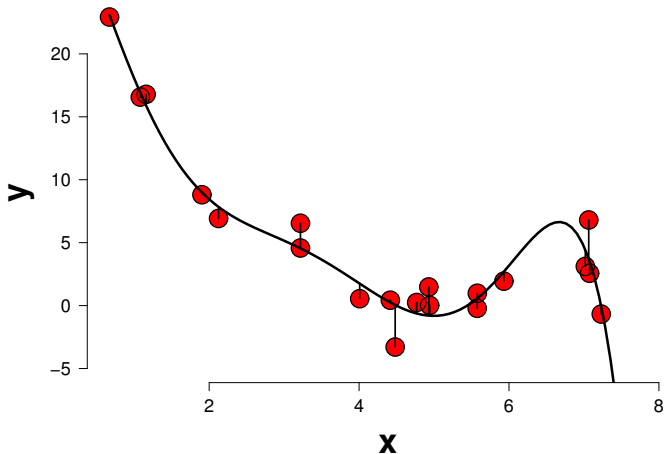
Learning on training set $p = 6$: In-sample error: 1.52

Goal of supervised learning

Generalisation: Out-of-sample error $p = 6$: 10.61

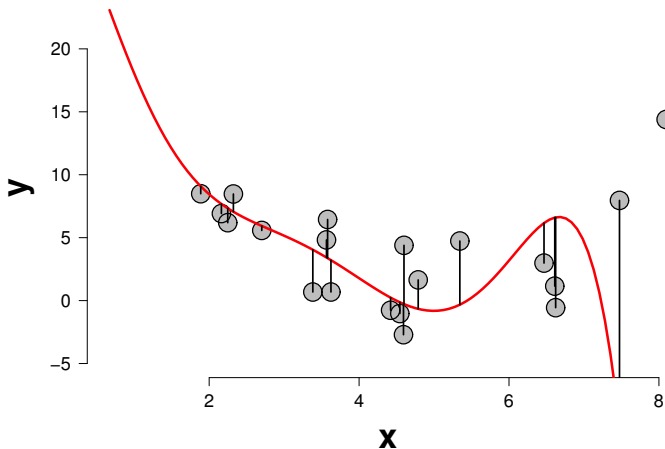


Goal of supervised learning

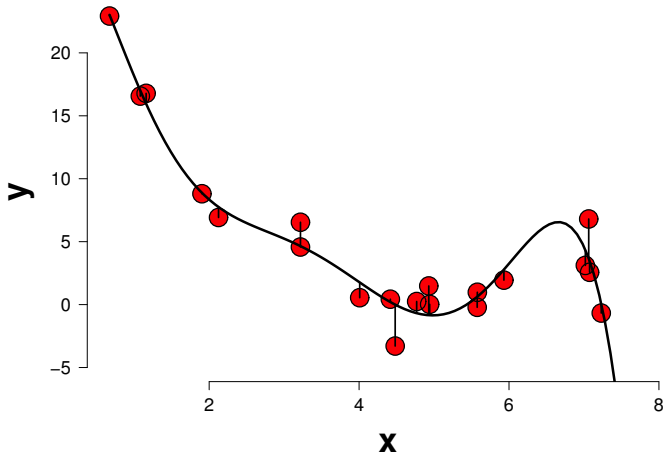
Learning on training set $p = 7$: In-sample error: 1.39

Goal of supervised learning

Generalisation: Out-of-sample error $p = 7$: 19.93

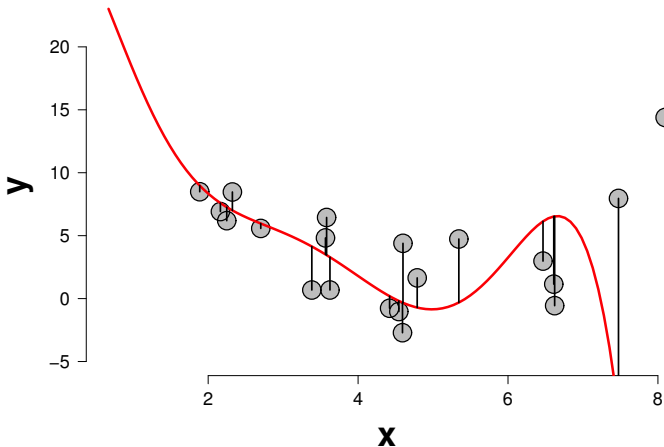


Goal of supervised learning

Learning on training set $p = 8$: In-sample error: 1.39

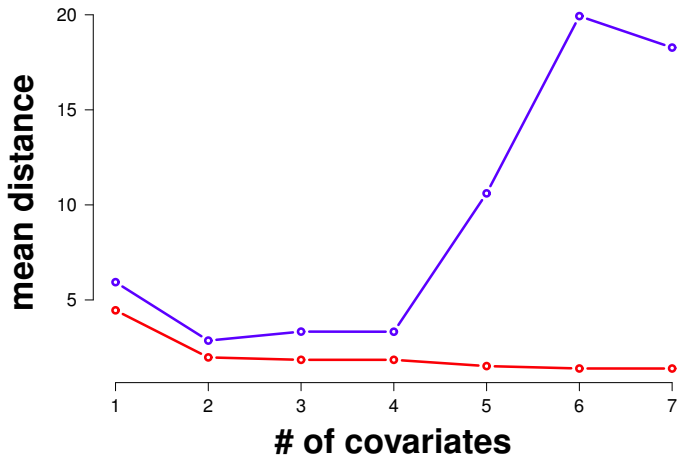
Goal of supervised learning

Generalisation: Out-of-sample error $p = 8$: 18.28



Goal of supervised learning

In-sample vs out-of-sample error



Summary

- Within sample error vs out-of-sample error
- Generalisation based on a point estimate: best guess
- Uncertainty quantification (within model): Bootstrapping (Quentin)
- Goal 2: Give an estimate prediction error use three-way splitting. Training set, cross validation set, test set. Cross validation (Johnny)
- Small to big model

How far can we go?

- The best guess was based on linear algebra: Write the problem in terms of

$$y = X\theta + \epsilon, \quad (7)$$

note: resulting best guess $\hat{f}(x)$ was polynomial, though, trick is to write it as a linear combination of basis functions: x^1, x^2, \dots, x^p .

- Minimiser is given by

$$\theta = (X^T X)^{-1} X^T y \quad (8)$$

where $X \in \mathbb{R}^{n \times p}$.

- Problem $n \ll p$: $X^T X$ is not invertible.

The $n \ll p$ regime: $X^T X$ is not invertible

- This means that there is not a unique solution: If θ_0 is such that $y = X\theta_0 + \epsilon$ then also $y = X(\theta_0 + u) + \epsilon$.
- Solution: Choose amongst all solutions, choose θ “small” by adding a penalty.

$$\hat{\theta} = \operatorname{argmin}_{\theta \in \mathbb{R}^p} \left\{ \frac{1}{n} \|y - X\theta\|_2^2 + \lambda \|\theta\|_q \right\} \quad (9)$$

Lasso: $q = 1$, Ridge: $q = 2$, Elastic net: combination of both.

- Regularisation: We add (Lagrange multiplier) constraints to make the singular matrix regular.

Same theme: Cross-validation

- Solution: Penalised regression

$$\hat{\theta} = \operatorname{argmin}_{\theta \in \mathbb{R}^p} \left\{ \frac{1}{n} \|y - X\theta\|_2^2 + \lambda \|\theta\|_q \right\} \quad (10)$$

- Candidate set: $\mathcal{F}_{\lambda,q} = \left\{ f(x) = X\theta \mid \|\theta\|_q = \lambda \right\}$
- Choose λ , use cross validation, see Johnny
- Different forms with $q = 1$, see Lourens.

Regression

- Goal: Give a *single* best guess $\hat{f}(x)$ of $f^*(x)$. Step 1: Define "**best** guess" aka define a **loss function**

$$E(f^*(x) - \hat{f}(x))^2 \quad (11)$$

- Step 2: Define a candidate collection of functions \mathcal{F}
- Step 3a: Find a good basis for \mathcal{F} use linear algebra trick to find the minimum
- Step 4a: Grow model $\mathcal{F}_{p,q,\lambda}$
- Step 5a: Regularise and cross validate

Regression problem: Y is continuous

- Different types of \mathcal{F} s:
 - Linear regression: Tahira
 - Polynomial, local, regression, splines: Alexander
- Choosing basis:
 - Smoothing splines, **Gaussian process priors**: Alexander
 - **Wavelets**
 - **Gabor patches**: Gilles
 - **Reproducing Hilbert space kernels**
 - Neural networks: Joost (composition basis)
- Multivariate X :
 - Generalised additive models (GAMs)
 - Regression trees: Riet
 - Gaussian graphical models: Lourens
 - **B-splines**

Classification problems: Y is discrete

- Different types of \mathcal{F} s:
 - Logistic regression: Lourens
- Multivariate X :
 - Classification trees: Riet
 - Support vector machines: Udo
 - k -nearest neighbours
 - random forests

Other topics

- Unsupervised learning:
 - Principle component analysis, independent component analysis
 - Clustering: Jonas
 - Topic modelling: Claire/Quentin
 - Mixture models and the EM algorithm
- Reinforcement learning:
 - Act-R: Leendert
 - Decision and game theory: Udo
 - Learning automata: Lourens
 - Bandit problems
 - Markov decision processes
- Internet stuff:
 - Page ranking: Johnny
 - Recommender systems: Don

Other topics

- State-space models:
 - Time series: Sacha
 - Kalman filters
 - Hidden markov models: Ingmar
 - Bayesian time series
 - Kriging: Gaussian processes
- Techniques
 - Boosting
 - Bayesian model averaging
 - More lassos
 - Stochastic gradient descent
 - Wavelets
- Applications:
 - Neural networks for psychological data
 - ...

Set-up

- Same set-up as last year. Do a presentation
- Requires a small peak in preparation of a talk
- Not necessary to understand everything. Can be practical and theoretical
- Still good to read things in advanced. Also website with literature, youtube clips are available.

Clustering

- Wednesday 23rd of November: 12.00 - 13.00
- Wednesday 23rd of November: 13.00 - 14.00
- ???